**LINK ARTICOLI**

# [An optimal trajectory planning algorithm for autonomous trucks: Architecture, algorithm, and experiment](https://journals.sagepub.com/doi/full/10.1177/1729881420909603)

[Time-optimal trajectory planning for a race car considering variable tyre-road friction coefficients](https://www.tandfonline.com/doi/full/10.1080/00423114.2019.1704804)

[Optimal control for a Formula One car with variable parameters](https://www.tandfonline.com/doi/full/10.1080/00423114.2014.889315?src=recsys)

ARTICOLI CHE NON CENTRANO COL PROGETTO, MA SECONDO ME SONO INTERESSATI

[Optimal tyre usage for a Formula One car](https://www.tandfonline.com/doi/full/10.1080/00423114.2016.1213861?src=recsys)

[Time-optimal control of the race car: influence of a thermodynamic tyre model](https://www.tandfonline.com/doi/full/10.1080/00423114.2011.622406?src=recsys)